

**IN THE CLAIMS:**

Please amend claim 3 as follows.

1. (Previously Presented) A method of computing finite impulse response (FIR) filter coefficients, comprising the steps of:

inputting a filter order of a universal maximally flat FIR filter, a number of zeros at  $z=-1$ , and a parameter for a group delay at  $z=1$ ,

wherein the filter order is a positive integer, the number of zeros is an integer equal to or more than zero, and the parameter is a rational number;

executing a first operation by a first recurrence formula which includes parameters for the filter order, the number of zeros, and the group delay, and provides coefficients in Bernstein form representation of a transfer function of the universal maximally flat FIR filter;

executing a second operation by a second recurrence formula comprising additions, subtractions, and divisions by 2, by using a resultant of the first operation as an initial value; and

extracting impulse response coefficients of the universal maximally flat FIR filter from a resultant of the second operation.

2. (Previously Presented) The method according to claim 1, wherein:

the first recurrence formula is expressed as

$b_j' = (-1)\{(2d) b_{j-1}' + (j - 1) b_{j-2}'\} / (N - j + 1)$  where  $1 \leq j \leq N$  with  $b_0' = 1$  and  $b_{-1}' = 0$ ,

wherein the filter order is  $N$ , the parameter for the group delay is  $d$ , coefficients in Bernstein form representation of a transfer function of the universal maximally flat FIR filter are  $b_j'$ ;

the resultant of the first operation is expressed as  $B' = \{1, b_1', \dots, b_{N-K}', 0, \dots, 0\}$ , wherein the number of zeros is  $K$ ;

the second recurrence formula is expressed as

$h_i^{(p)} = (1 + E) h_i^{(p-1)} / 2 + (1 - E) h_{i-1}^{(p-1)} / 2$  where  $1 \leq p \leq N$ ,  $0 \leq i \leq p$ , with  $h_0^{(0)} = B'$  and  $h_{-1}^{(p)} = \{0, \dots, 0\}$ ,

wherein a sequence for computing impulse response coefficients of the universal maximally flat FIR filter is expressed as  $h_i^{(p)} = (h_{i,j}^{(p)}) = (h_{i,0}^{(p)}, h_{i,1}^{(p)}, \dots)$ , and an arbitrary sequence  $A_i$  is expressed as  $E^j = E (E^{j-1} A_i)$ ,  $E^1 A_i = E A_i = A_{i+1}$ ,  $E^0 A_i = A_i$  in which a forward shift operator satisfying the expression is  $E$ ; and

the impulse response coefficients extracted from the resultant of the second operation are expressed as  $h_i = h_{i,0}^{(N)}$  where  $0 \leq i \leq N$ .

3. (Currently Amended) A program for computing finite impulse response (FIR) filter coefficients embodied on a computer readable medium, the program causing a computer to execute the steps of:

determining every element of a single-dimension array  $B'$  using a filter order  $N$ , a number of zeros  $K$  at  $z=-1$ , and a parameter  $d$  for a group delay at  $z=1$ , by changing in sequence an index  $j$  from 1 to  $N-K$  in a recurrence formula  $B'[j] = (-1) \times \{(2d)B'[j-1] + (j-1)B'[j-2]\} / (N - j + 1)$ , the single-dimension array having  $N+1$  elements  $B'[j]$  where  $0 \leq j \leq N$ , in which an element  $B'[0]$  thereof is initialized to 1 and all the elements thereof except the element  $B'[0]$  are initialized to zero;

wherein  $N$  is a positive integer of a universal maximally flat FIR filter,  $K$  is an integer equal to or more than zero,  $d$  is a rational number, and  $N$ ,  $K$ , and  $d$  are provided by inputs;

determining every element of a three-dimension array  $r$  by sequentially changing, in the order of indexes  $j, i, p$ , an index  $j$  from 0 to  $N-p$ , and an index  $i$  from 0 to  $p$ , an index  $p$  from 1 to  $N$  in a recurrence formula  $r[p,i,j] = (r[p-1,i-1,j] - r[p-1,i-1,j+1]) / 2 + (r[p-1,i,j] + r[p-1,i,j+1]) / 2$ , the three-dimension array  $r$  having  $N^3$   $(N+1)^3$  elements  $r[p,i,j]$  where  $0 \leq p \leq N$ ,  $0 \leq i \leq N$ ,  $0 \leq j \leq N$ , in which elements  $r[0,0,j]$  thereof where  $0 \leq j \leq N-K$  are initialized to elements of the single-dimension array  $B'[j]$  where  $0 \leq j \leq N-K$ , and all the elements thereof except the elements  $r[0,0,j]$  are initialized to zero; and

extracting elements  $r[N,i,0]$  of the three-dimension array  $r$  where  $0 \leq i \leq N$  as the impulse response coefficients of the universal maximally flat FIR filter.